

CE1.1-R4 : DIGITAL SIGNAL PROCESSING**NOTE :**

1. Answer question 1 and any FOUR from questions 2 to 7.
2. Parts of the same question should be answered together and in the same sequence.

Time : 3 Hours**Total Marks : 100**

1. (a) A system is given as $y(n) = |x(n)|$. Determine whether it is stable, causal, linear or time-invariant.
- (b) Evaluate the step response for the LTI system represented by the impulse response

$$h(n) = \left(-\frac{1}{2}\right)^n u(n)$$
- (c) Compute the convolution $y(n) = h(n) * x(n)$ for the following signals,
 $x(n) = (0.8)^n u(n)$ and $h(n) = (0.4)^n u(n)$
- (d) Determine the z-transform of the signal $x(n) = nu(n)$.
- (e) Determine and sketch the magnitude and phase response of the following system
 $y(n) = x(n) - x(n-10)$
- (f) If $x(n)$ has a N-point DFT $X(k)$, find the N point DFT of the signal

$$y(n) = \cos\left(\frac{2\pi n}{N}\right) x(n)$$
- (g) Perform the circular convolution of the following two sequences.
 $x_1(n) = \delta(n) + 2\delta(n-1) + 2\delta(n-2)$
 $x_2(n) = \delta(n) + 2\delta(n-1) + 3\delta(n-2) + 4\delta(n-3)$

(7x4)

2. (a) A causal LTI system has a system function

$$H(z) = \frac{1}{1 - 1.04z^{-1} + 0.98z^{-2}}$$
 - (i) Is this system stable ?
 - (ii) If the coefficients are rounded to nearest tenth, then would the resulting system be stable ?
- (b) Design a Chebyshev IIR digital low-pass filter to satisfy the following specifications :
 $0.707 \leq |H(\omega)| \leq 1, \quad 0 \leq |\omega| \leq 0.2\pi$
 $|H(\omega)| \leq 0.1, \quad 0.5\pi \leq |\omega| \leq \pi$
 Using bilinear transformation and assuming $T = 1s$
- (c) Determine the variance of the noise generated by the analog-to-digital quantization noise at the output of a first-order stable digital filter with transfer function

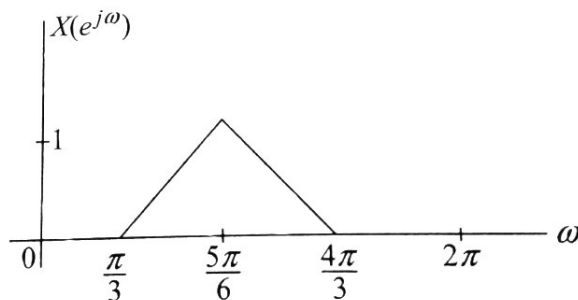
$$H(z) = \frac{1}{1 - az^{-1}}$$

(5+8+5)

3. (a) Design a eighth order high-pass FIR filter using Hamming window, with a cutoff frequency of 1.2 rad/sec.
 (b) Explain the various addressing modes used in DSP processors.
 (c) Explain the Von Neumann and Harvard architectures in brief.

(8+5+5)

4. (a) Consider the sequence $x(n]$ with $X(e^{j\omega})$ as shown in the figure. Let $y(n) = x(2n)$ be the down sampled version of $x(n)$. Show how we can recover $x(n)$ from $y(n)$ using filters and multirate building blocks.



- (b) A frequently used model for the generation of echo is $y(n) = \sum_{k=0}^{\infty} \alpha_k x[n-kT]$, where $x(n)$ is the digitized version of the original music signal, T is the interval between echoes and α_k is the gain for the k -th echo of the original signal. Show that the comb filter with system function $H(z) = \frac{1}{1-az^{-1}}$ can be used to generate artificial echoes. Also give a possible realization of the system.

(9+9)

5. (a) An LTI system is described by the difference equation.

$$y(n) - \frac{9}{4}y(n-1) + \frac{1}{2}y(n-2) = x(n) - 3x(n-1)$$

Specify the ROC of $H(z)$ and determine $h(n)$ for the following conditions

- (i) The system is stable
 (ii) The system is causal.
- (b) Consider a 4-point sequence $x(n) = \{1, 2, 3, 4\}$. Use Goertzel algorithm to compute DFT coefficient $X(k)$ at frequency bin $k=1$
- (c) Using the signal flow graph method DIF-FFT, determine the 8-point DFT of the sequence $x(n) = \{1, 1, 1, 1\}$. Show the intermittent values of the graph.

(6+6+6)

6. (a) A FIR digital filter is characterized by the following transfer function (filter length $M=11$)

$$H(z) = \sum_{n=0}^{M-1} h(n)z^{-n}$$

Determine the amplitude response and show that phase and group delay of the causal filter are constant.

- (b) Show how an inverse DFT can be obtained by using direct DFT method. Draw the signal flow graph for a 4-point DFT by DIT-FFT algorithm. Explain how the same signal flow graph can be used to compute inverse DFT.

(9+9)

7. (a) Show that with $x(n)$ as a N -point sequence and $X(k)$ as its N -point DFT,

$$\sum_{n=0}^{N-1} |x(n)|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |X(k)|^2$$

- (b) Determine the lattice coefficients corresponding to the FIR system with the system function

$$H(z) = 1 + \frac{7}{9}z^{-1} + \frac{3}{5}z^{-2}, \text{ and realize it.}$$

- (c) Obtain the direct form-I and direct form-II realizations of the LTI system governed by the equation

$$y(n) = -\frac{13}{12}y(n-1) - \frac{9}{24}y(n-2) - \frac{1}{24}y(n-3) + x(n) + 4x(n-1) + 3x(n-2)$$

(5+6+7)

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